

5^{to} FORO

en Seguridad de la Información

RETOS Y SOLUCIONES

PARA LA PRIVACIDAD EN UN MUNDO CONECTADO

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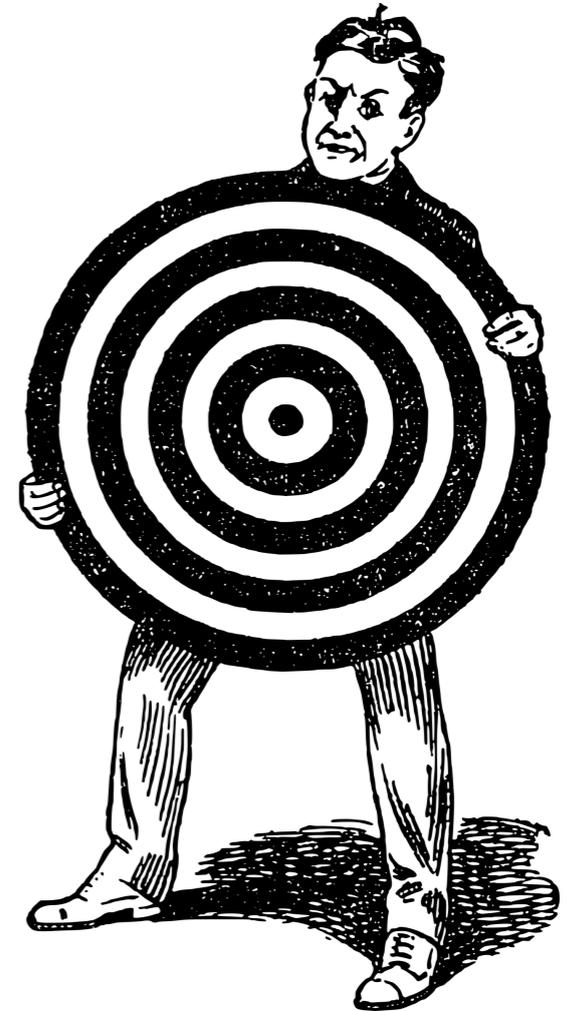
Reconocimiento como Universidad: Decreto 1297 del 30 de mayo de 1964 | Reconocimiento Personería Jurídica: Resolución 28 del 23 de febrero de 1949 Minjusticia.

Location privacy

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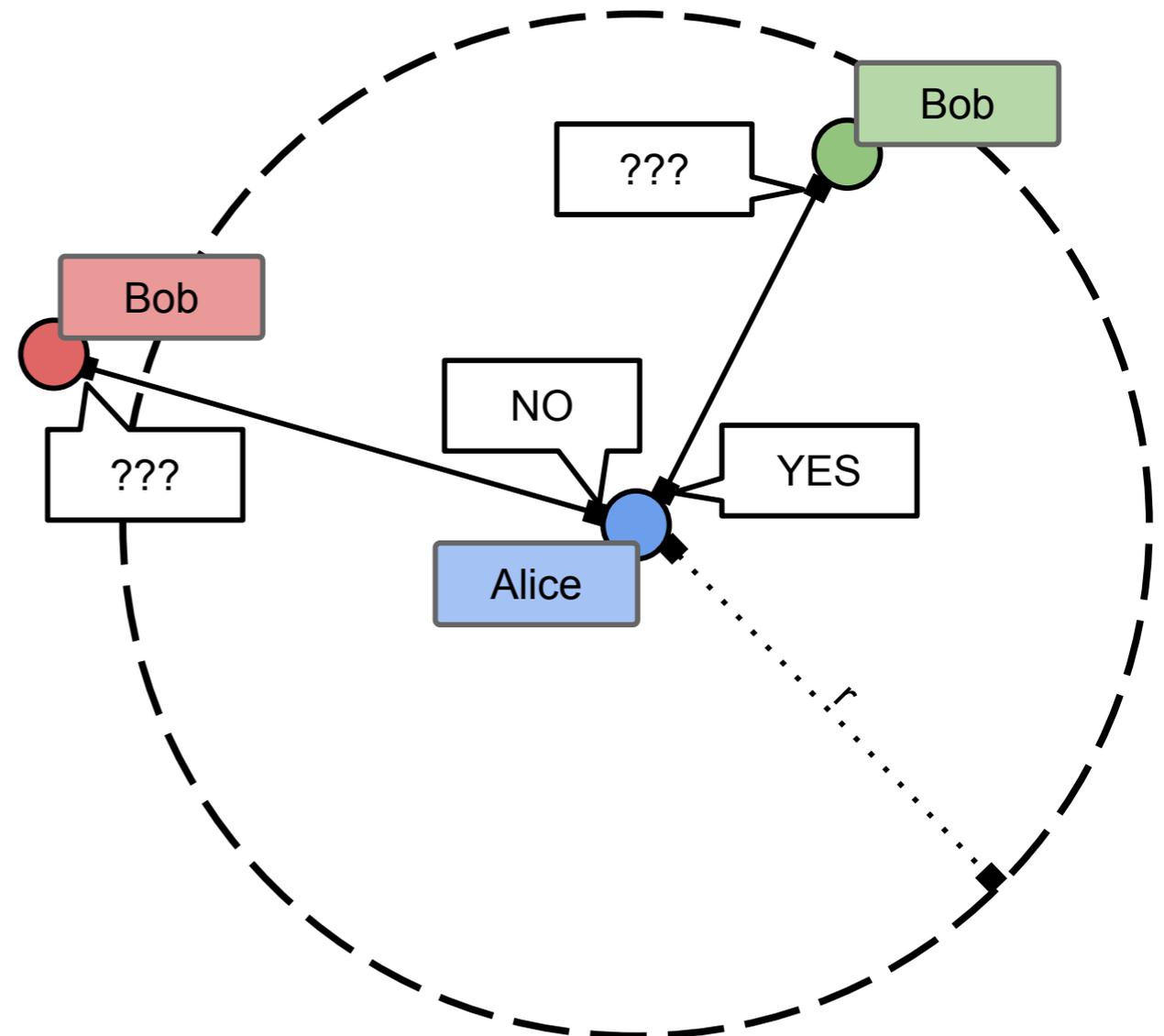
Motivation

- ❖ GPS enabled devices are ubiquitous
- ❖ Location-Based services are increasingly powerful
- ❖ Implementations of location-based services have been attacked
 - Include Security attack to locate any Tinder user, Feb 2014
 - "Girls around me" stalking app abusing Foursquare APIs, March 2012

Running example

❖ Finding friends

- Alice: is Bob close by (within r)?
 - Bob: yes/no



Problem

- ❖ How do we achieve utility and privacy?
- ❖ In other words, how do we share location securely?
 - ❖ *Exact location*: not private
 - ❖ *Distance*: triangulation attacks
 - ❖ *Obfuscated distance*: still possible to triangulate or loss of utility
 - ❖ *To third party*: Do we trust third party?

Outline

- ❖ Preliminaries
- ❖ One solution: **InnerCircle**
- ❖ An improvement: **BetterTimes**
- ❖ A further enhancement: **MaxPace**
- ❖ Triangulation: **Grids**
- ❖ Moving targets
- ❖ Work in Progress / Future Work

Secure Multi-party Computation

- ❖ Location proximity is an instance of a multi-party computation:

$$f(\text{location_A}, \text{location_B}) = \begin{cases} 1 & \text{if close,} \\ 0 & \text{otherwise} \end{cases}$$

- ❖ Very similar to original Millionaire's Problem (Yao).
- ❖ Solvable i.e. with Garbled Circuits, Fully Homomorphic encryption.

Homomorphic Encryption

- ❖ An encryption function $[[\]]$ is additively homomorphic if:

$$[[a]] + [[b]] = [[a + b]]$$

- ❖ It follows:

$$[[a^*m]] = [[a]]^*m$$

InnerCircle

❖ Note that:

$$\begin{aligned} \llbracket d^2 \rrbracket &= \llbracket (x_A - x_B)^2 + (y_A - y_B)^2 \rrbracket = \dots \\ &= \llbracket x_A^2 + y_A^2 \rrbracket \oplus \llbracket x_B^2 + y_B^2 \rrbracket \ominus ((\llbracket x_A \rrbracket \odot 2x_B) \oplus (\llbracket y_A \rrbracket \odot 2y_B)) \end{aligned}$$

❖ It follows:

$$\llbracket (d^2 - 0) \cdot r_0 \rrbracket, \llbracket (d^2 - 1) \cdot r_1 \rrbracket, \dots, \llbracket (d^2 - r^2) \cdot r_{r^2} \rrbracket$$

contains a 0 iff $d < r$.

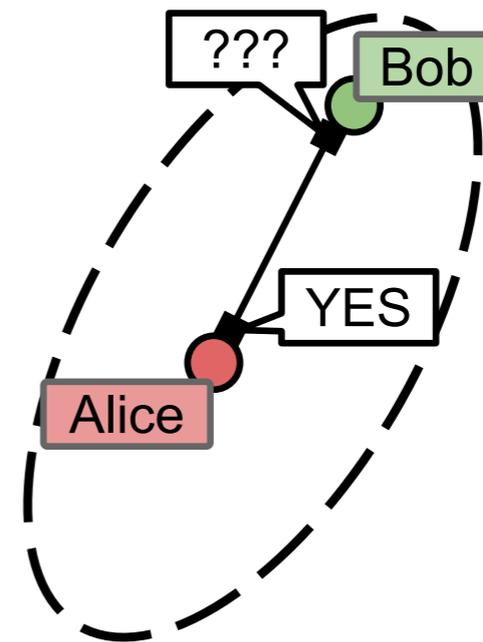
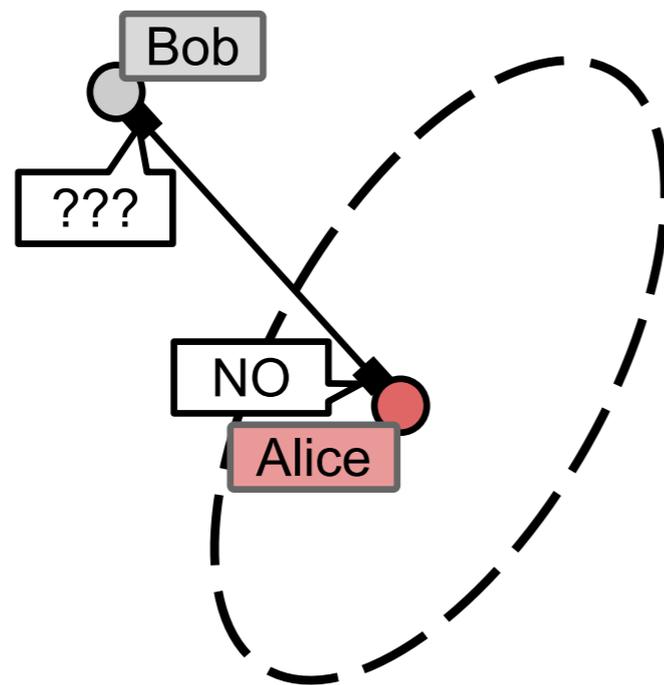
❖ InnerCircle is provably secure against semi-honest adversaries.

InnerCircle

- Results
 - Under one second
 - $r=80$ with 80 bits of security
 - $r=30$ with 112 bits of security
 - Faster than competing solutions
 - $r = 50$ for 80 bits of security
 - $r = 75$ for 112 bits of security
- Parallelization boosts performance almost linearly.

Malicious attackers

Malicious



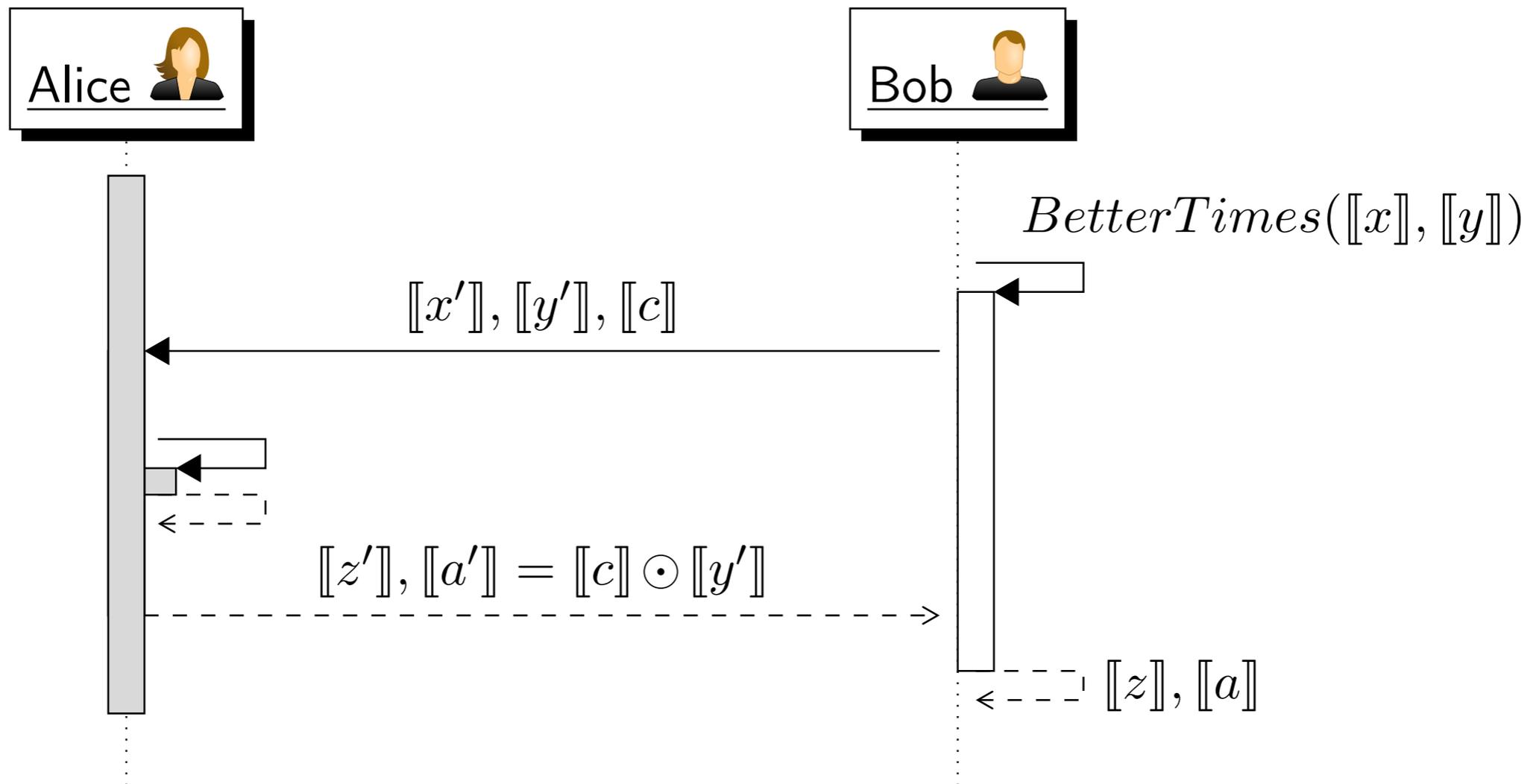
- $\alpha = x_A$
- $\beta = y_A$
- $\gamma = x_A^2 + y_A^2$

Alice sends α, β and γ s.t. $\gamma \neq \alpha^2 + \beta^2$

BetterTimes

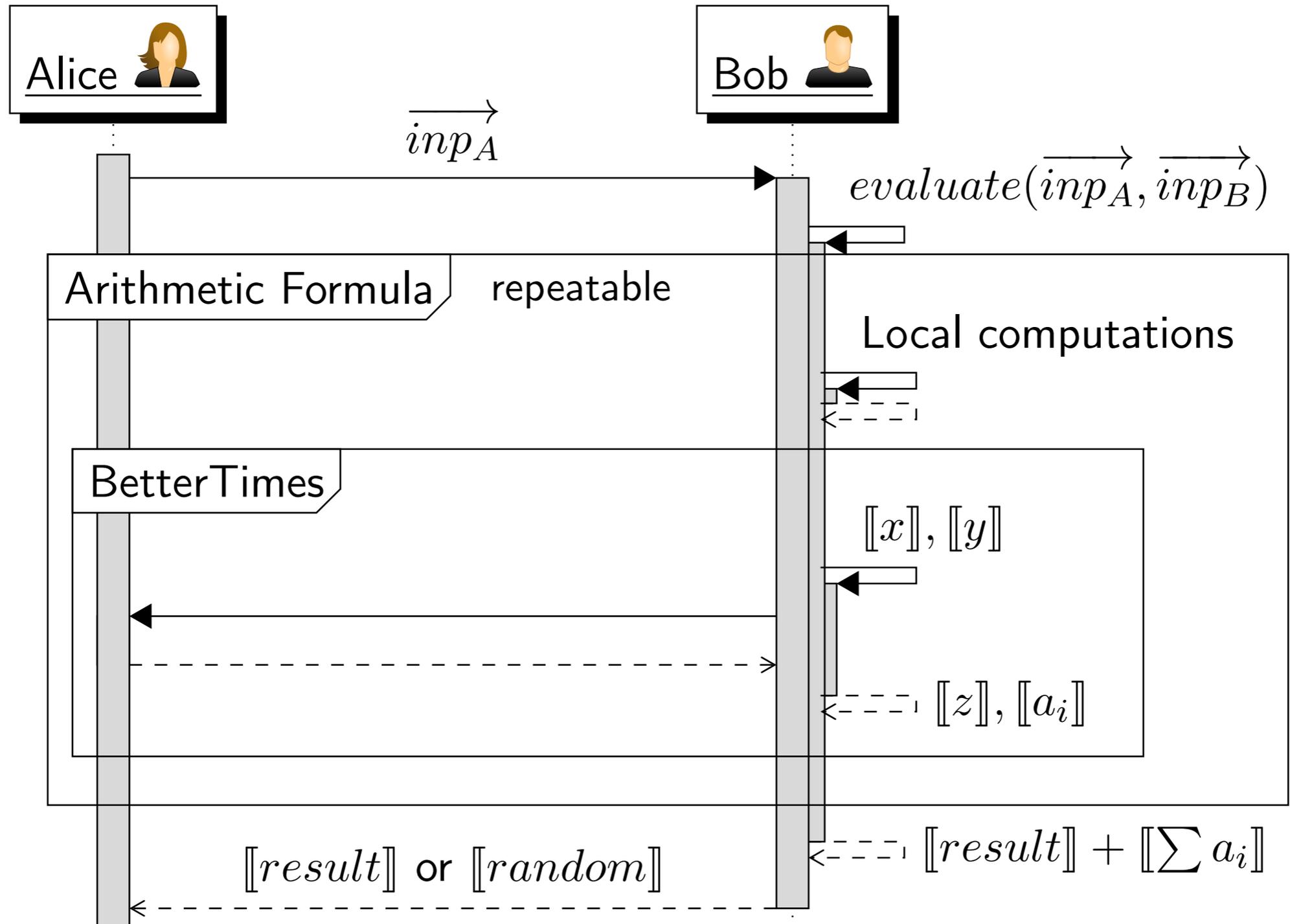
- ❖ From $[[x]]$ we cannot compute $[[x^2]]$.
- ❖ Missing operation: $[[x]] * [[y]]$.
- ❖ Idea: Outsource operation to Alice such that if result $[[z]] \neq [[x * y]]$ then result of functionality is garbled.

BetterTimes

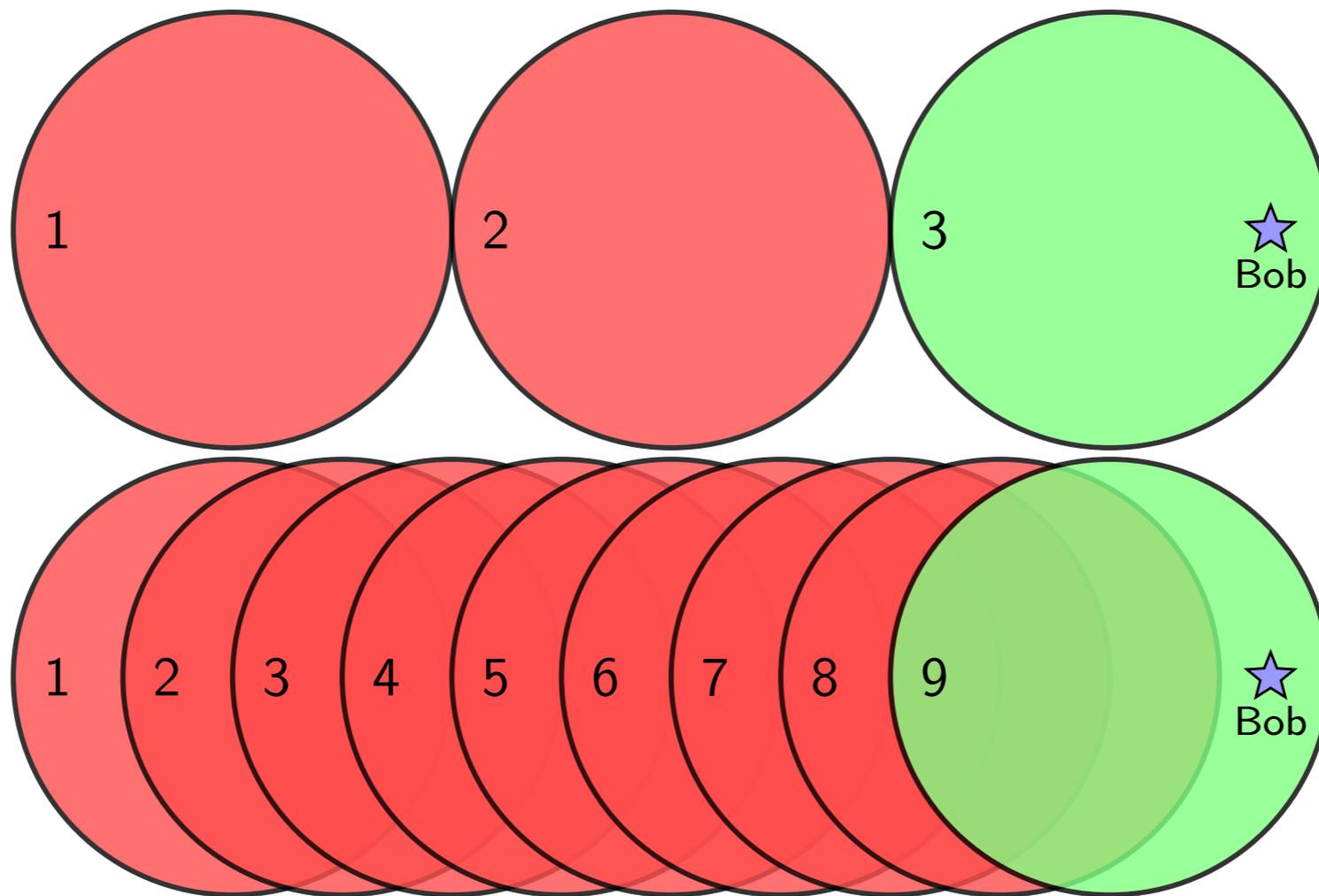


$$\llbracket a \rrbracket = (\llbracket a' \rrbracket \ominus (\llbracket z' \rrbracket \oplus \llbracket y' \rrbracket \odot c_a) \odot c_m) \odot \rho, \text{ with } \rho \text{ random}$$

BetterTimes



Swiping the plane



MaxSpace

- ❖ Simple idea: force attacker to swipe the plane slower by limiting speed.
- ❖ **Key insight:** We can compute speed homomorphically and garbled output of proximity request if attacker moves too fast.

MaxSpace

TABLE I: Speeds in m/s and km/h for the used scenarios

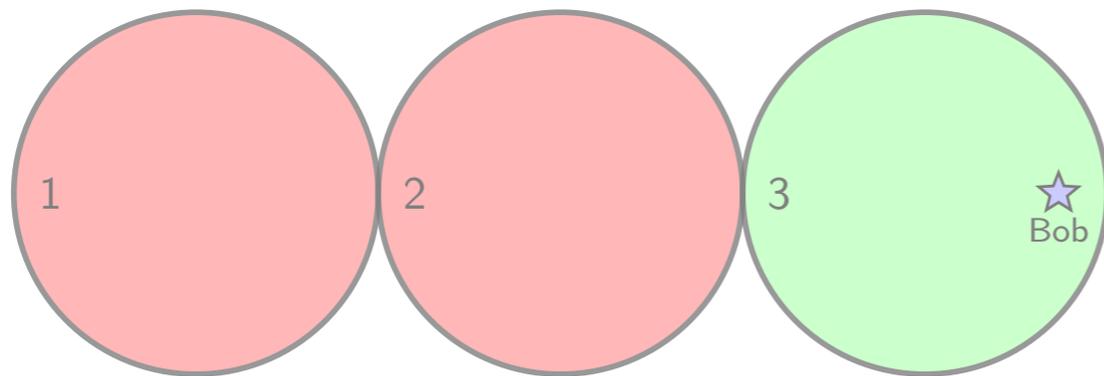
| Activity | Walking | Running | Cycling | Bus | Car (highway) |
|----------|---------|---------|---------|------|---------------|
| m/s | 2 | 3 | 5 | 14 | 33 |
| km/h | 7.2 | 10.8 | 18 | 50.4 | 118.8 |

TABLE II: Bounds for different speed radiuses

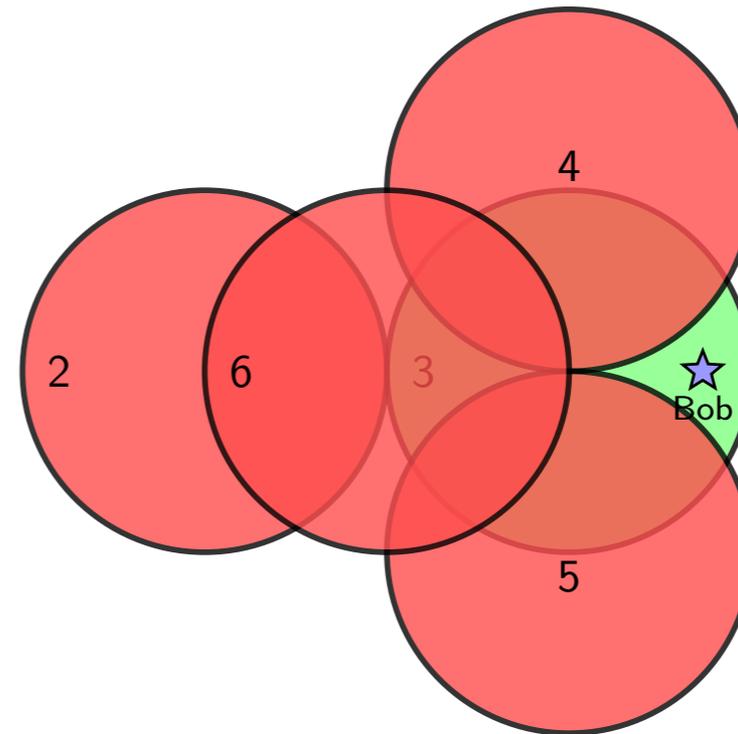
| Speed | Radius | | | |
|---------|--------|-------|-------|-------|
| | 10 | 25 | 50 | 100 |
| Walking | 78.2 | 194.3 | 384.4 | 752.7 |
| Running | 52.2 | 130.0 | 258.1 | 508.8 |
| Cycling | 31.4 | 78.2 | 155.7 | 308.8 |
| Bus | 11.2 | 28.0 | 55.9 | 111.5 |
| Car | 4.8 | 11.9 | 23.8 | 47.5 |

Triangulation

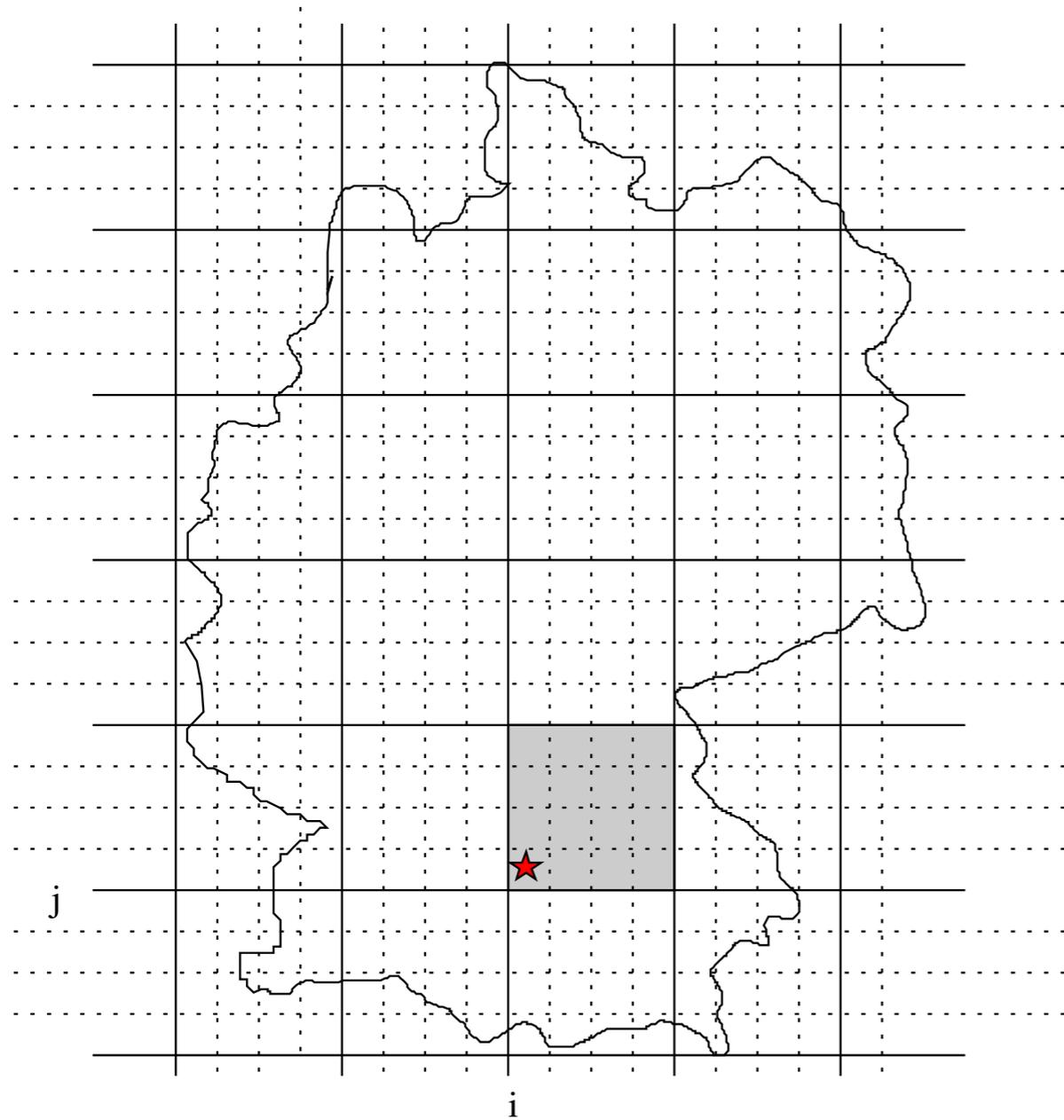
DiskCoverage



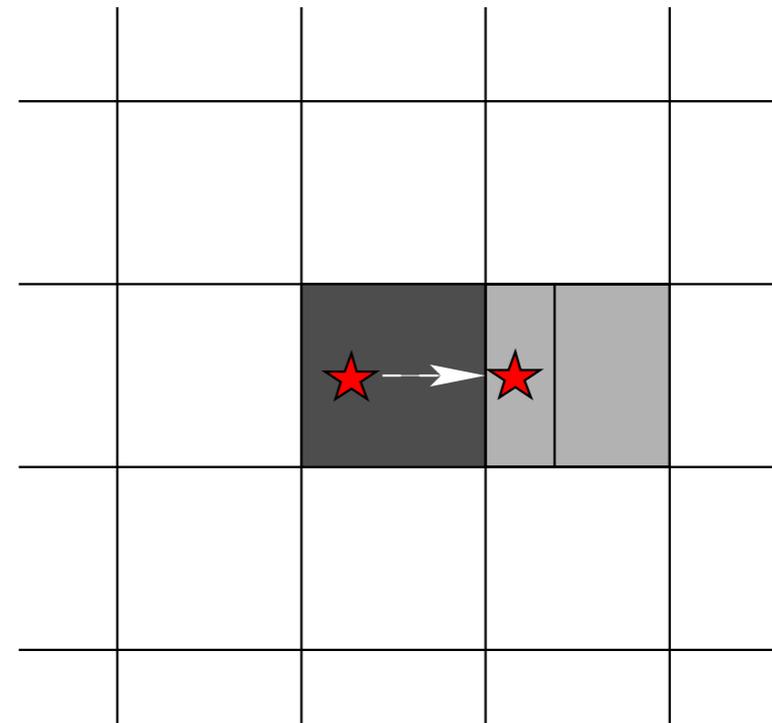
DiskSearch



Grids

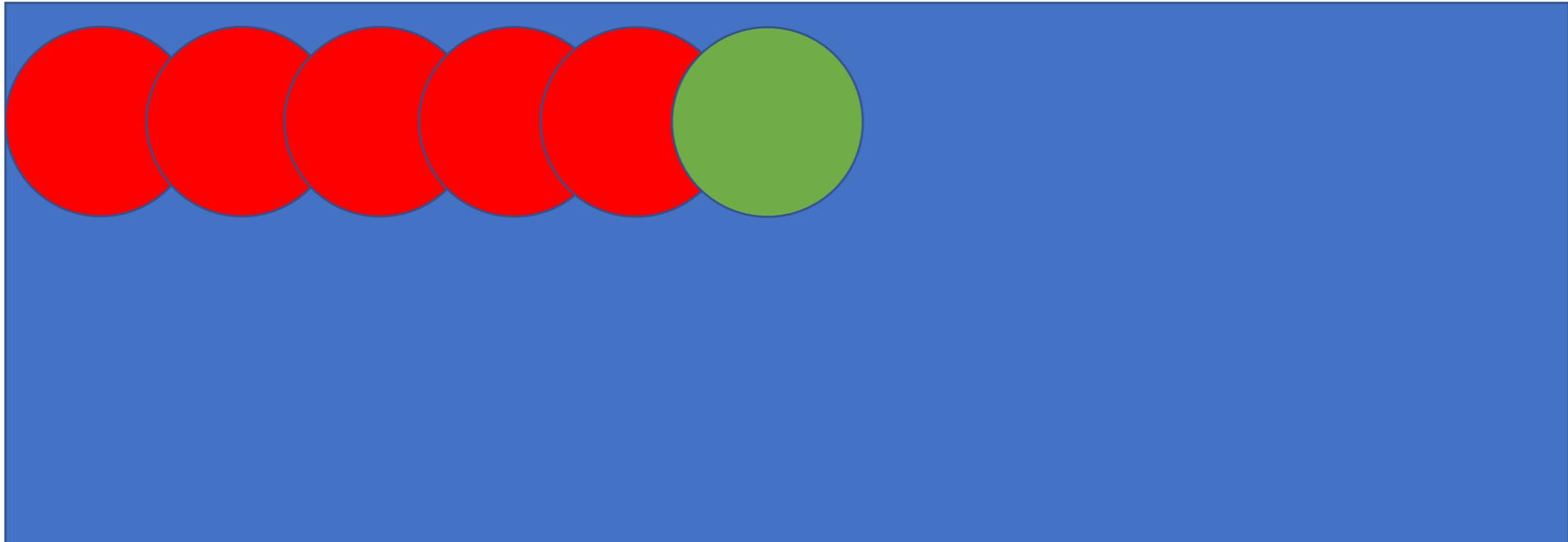


Problem:



Moving targets

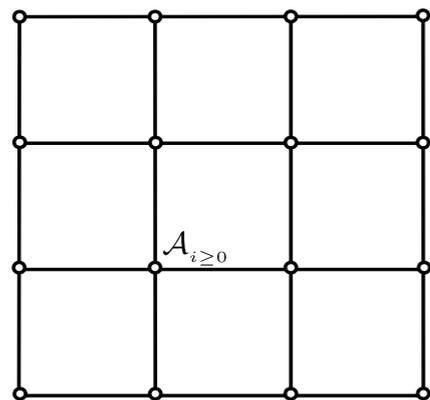
- ❖ Typically attacks in this setting involve "parsing" the plane, to then triangulate:



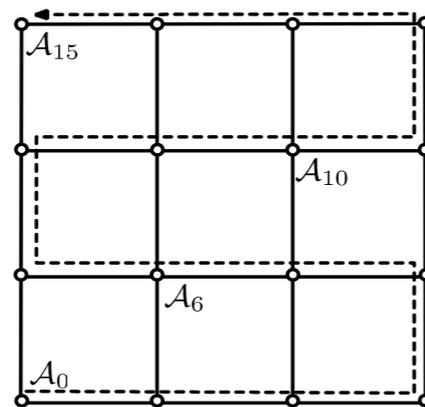
- ❖ But what if victim is moving? Should an attacker revisit some of previous guesses? What is his best strategy?

Moving targets

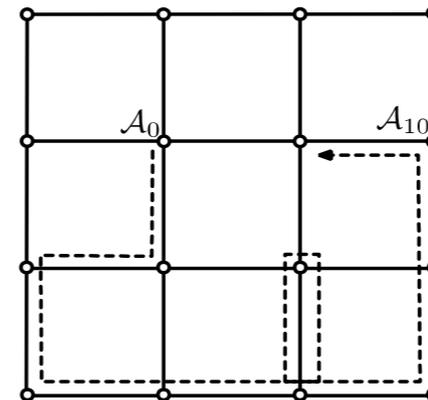
- ❖ We consider abstract attacks where both **the target and the attacker move** according to a particular mobility pattern



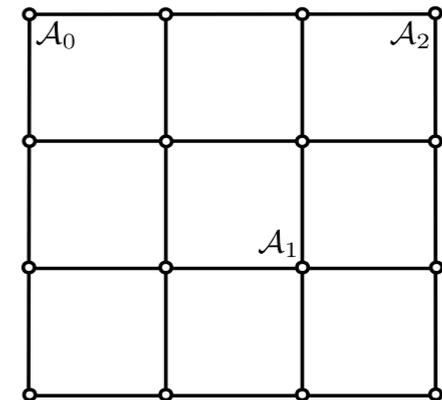
static



linear



random walk



random jump

- ❖ Our goal is to determine the **attacker effort** to locate the target with a probability of at least p (usually $p = \frac{1}{2}$).

Events of interest

- ❖ We are interested in the probability of two events:
 - ❖ E_k : is the event that Alice locates Bob **within** k steps (i.e., $k + 1$ queries)

$$E_k := \{\exists i \leq k \text{ s.t. } \mathcal{A}_i = \mathcal{B}_i\}$$

- ❖ F_j : is the event that Alice locates Bob in **exactly** j steps

$$F_j := \{\mathcal{A}_j = \mathcal{B}_j\}.$$

Bounds

- ❖ An **upper bound** on $\Pr(E_k)$ gives a **lower bound** on k :
 - ❖ If after k steps you have at **most** probability $p \Rightarrow$ need at least k steps to reach p .
 - ❖ This is relatively easy to compute with the formula on previous slide.

- ❖ A **lower bound** on $\Pr(E_k)$ gives an **upper bound** on k :
 - ❖ If after k steps you have at least probability $p \Rightarrow$ need at most k steps to reach p .
 - ❖ This is harder, it needs a concrete attack strategy to realize an upper bound to p .

Lines vs. Planes

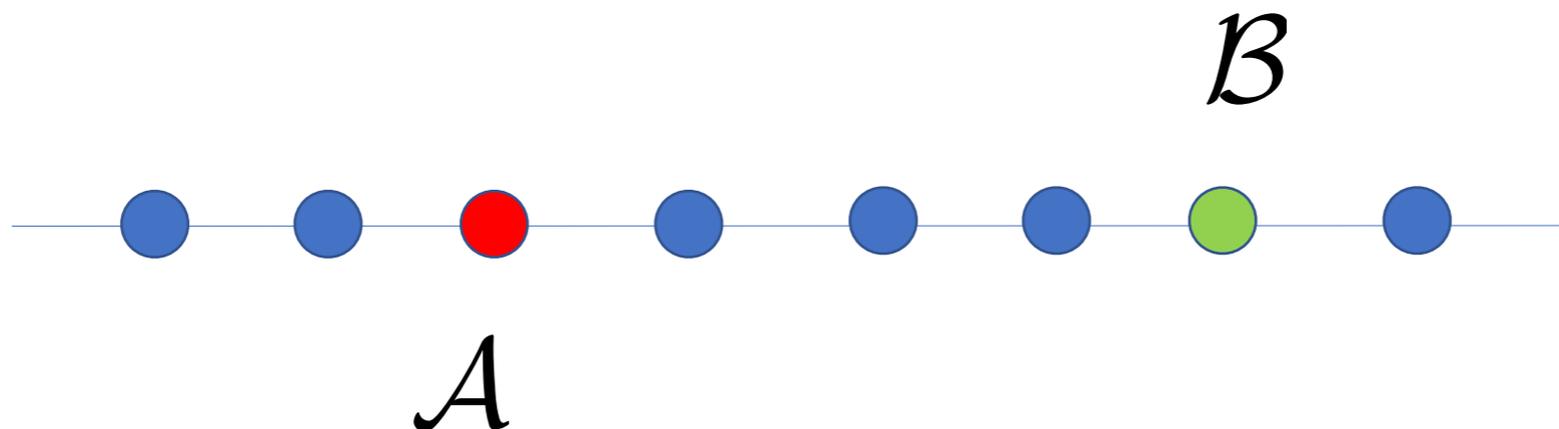
- ❖ We first tackle the problem when the space is linear and obtain (rigorous) bounds **for *any* attacker and for *any* space size n** when the victim moves in a random walk.
 - ❖ In this case the structure of the matrix P allows for easier algebraic bounds
 - ❖ We can test this also numerically.
- ❖ In the plane, it is much harder to analytically derive such bounds. Numerically we obtain similar bounds.
 - ❖ Matrix structure is more complex in this case!

Random Walk Example

Theorem: Considering a random-walking victim, a search space of size n and a probability $\frac{1}{2}$, we have that:

$$\sum_{i=0}^k \max_j B_j^{(i)} \longrightarrow \lfloor \frac{n}{3} \rfloor - 1 \leq k_O \leq \lfloor \frac{n}{2} \rfloor \longleftarrow \text{Linear Jump}$$

for a linear search space.



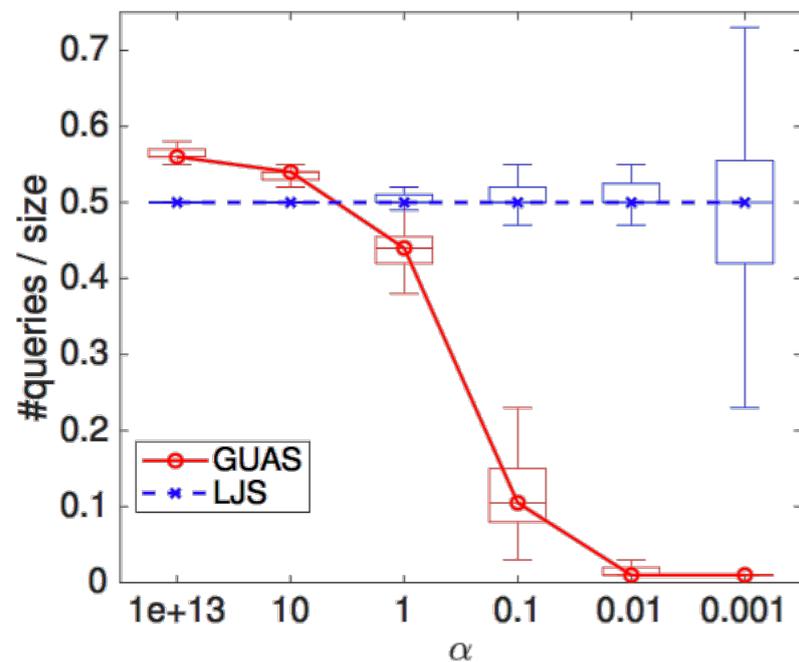
Results on Random Walks

- ❖ *Linear Jumping Strategy (LJS)*

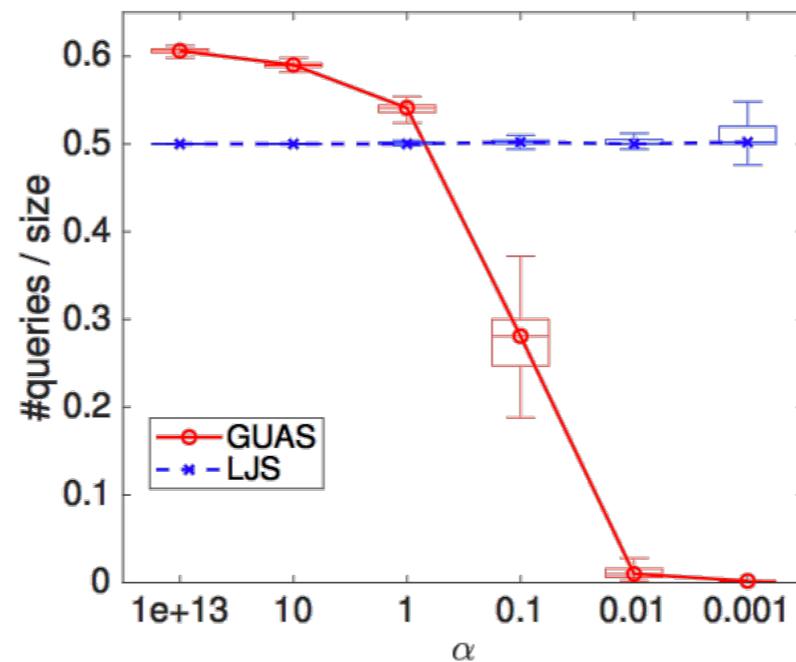
- ❖ Achieves the optimal lower bound when the victim's initial position distribution is almost uniform (i.e., large alpha)

- ❖ *Greedy Updating Attack Strategy (GUAS)*

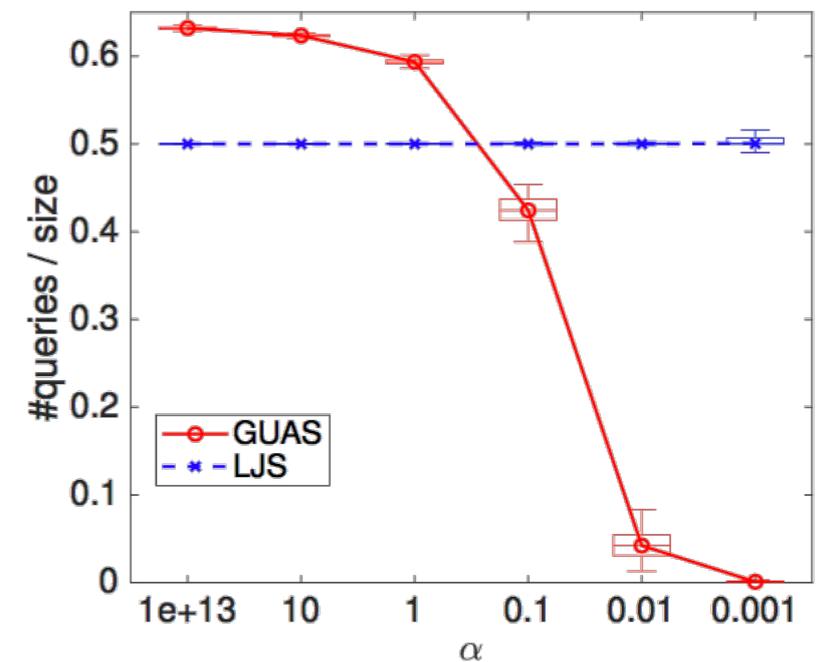
- ❖ More effective than LJS for non-uniform initial distributions



(a) Search space size = 100



(b) Search space size = 500



(c) Search space size = 2000

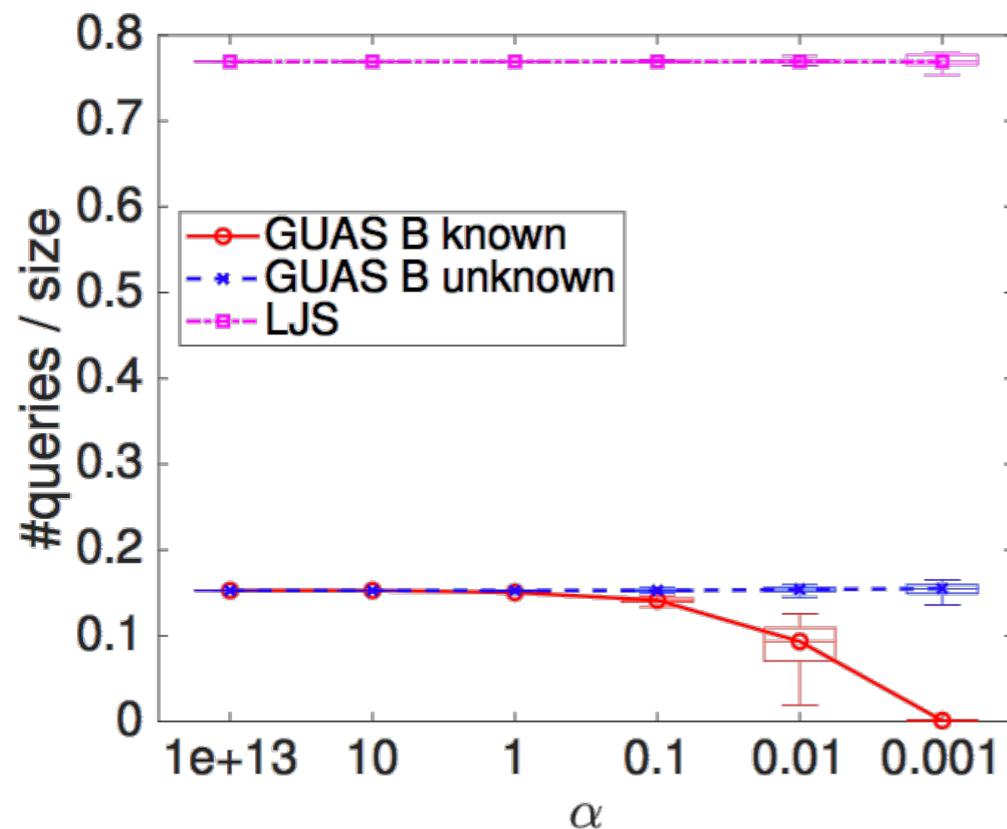
Evaluation with real mobility models

- Finally, we evaluated the performance of these strategies with a real-world dataset
- We **derived a transition matrix** P_{taxi} from the Beijing Dataset
 - GPS trajectories of taxis from city of Beijing (3rd ring).
 - The area is discretized into 884 locations of 500 x 500m
 - Average sampling interval is around 177 seconds

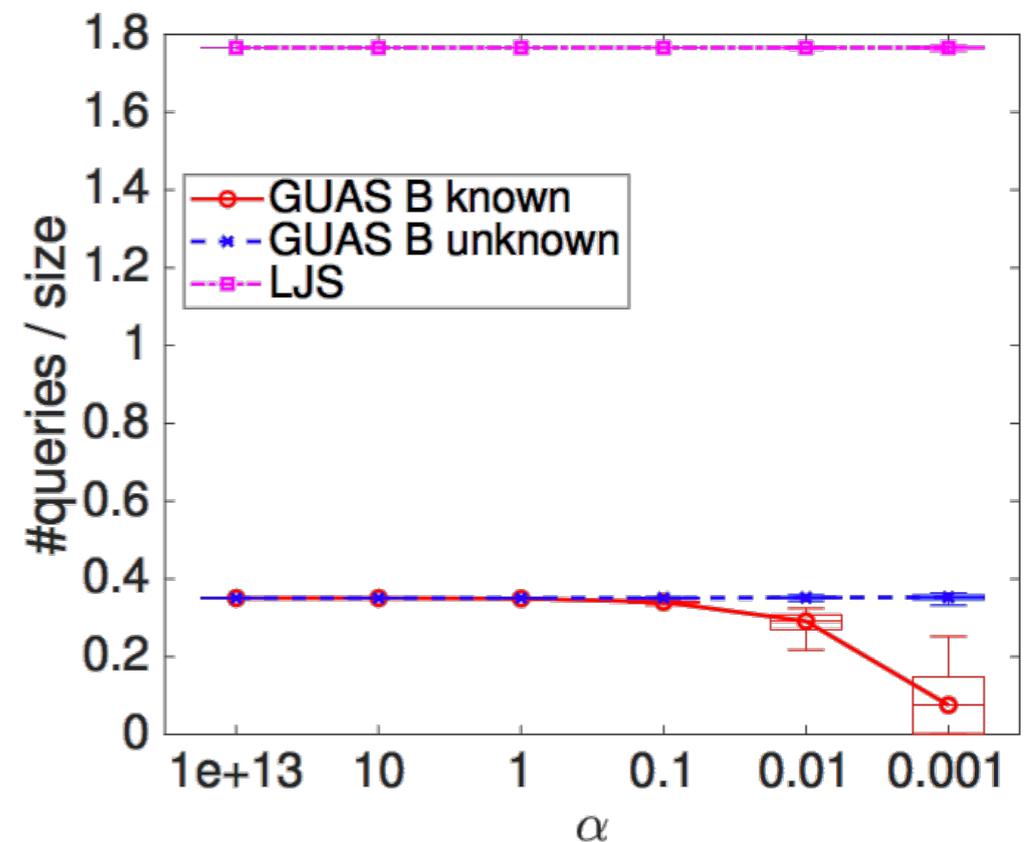


Results on realistic dataset

- Our results show that **GUAS** performs significantly **better** than LJS for more realistic mobility patterns
 - GUAS consistently requires less than $N/6$ queries for $p=0.5$
 - LJS requires more than $0.75N$ queries



(a) Performance with $p=0.5$



(b) Performance with $p=0.8$

Conclusions

- ❖ We establish a **general formula** for calculating the probability of the attacker finding the victim after any number of queries
- ❖ We give **upper and lower bounds** on the minimum number of queries to locate a victim with a given probability
 - ❖ An optimal attacker needs at most $M/2$ queries with probability $1/2$
- ❖ We implement **two attacker strategies** (LJS, GUAS) and evaluated them in the case of
 - ❖ Random walk victim
 - ❖ Realistic mobility dataset
- ❖ GUAS strategy **performs** significantly better with realistic mobility patterns
 - ❖ The attacker targets the victim in 134 steps (6.6 hours) with probability $1/2$

Future Work

- We consider the evaluation of some countermeasures
 - The LBS probabilistically returns a wrong result
 - The LBS could verify that location claims conforms to some assumed transition matrix P
 - The LBS could impose limitations on the number of queries or the speed / frequency of queries
- ❖ Evaluation with different mobility models for different modes of transport
- ❖ Consider more powerful attackers (e.g., colluding)
- ❖ Devise new attacker “optimal” strategies

References

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